

Running Gazebo Simulator

Next build everything by running `catkin_make`. Then run the following command:

```
roslaunch robosub_simulator gazebo.launch
```

this will load the proper param files, start up gazebo with the correct world, spawn the sub, and finally, start the simulator bridge.

From:

<http://robosub-vm.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:

<http://robosub-vm.eecs.wsu.edu/wiki/cs/simulator/run/start?rev=1481585596>



Last update: **2016/12/12 15:33**