

Using ROS Node

This command allows the user to gather information about any running node.

Getting Node Info

```
roscpp info <NODE>
```

Pinging a Node

```
roscpp ping <NODE>
```

Listing Running Nodes

```
roscpp list
```

Get a List of All Machines on the Network

```
roscpp machine
```

Get a List of Nodes Running on a Machine

```
roscpp machine <MACHINE_NAME>
```

Kill a Running Node

```
roscpp kill <NODE>
```

Clean the Server of Unresponsive Nodes

```
roscpp cleanup
```

From:
<https://robosub-old.eecs.wsu.edu/wiki/> - **Palouse RoboSub Technical Documentation**

Permanent link:
<https://robosub-old.eecs.wsu.edu/wiki/cs/ros/rosnode/start>

Last update: **2017/01/18 17:32**



